## Operating Procedure

## IO-Link Gateway

## UC2-IOL

OPTEX FA CO. LTD.

The following operating procedure is for checking or changing setting values in a D3RF, D3WF, CDA, CD22 (via CDA) or TD1 (via CDA) connected to the UC2-IOL via IO-Link.

* Refer to the UC2-IOL address list or the address list of the connected module being configured.


## General Description

IO-Link is used to connect the UC2-IOL to the IO-Link master unit, and a proprietary interface is used to connect the UC2-IOL to the connected modules (D3RF, etc.)


This means IO-Link should be used to check or change setting values in the connection module from the IO-Link master unit, and access should be through UC2-IOL module communication (address 262) and module data (address 263)

Refer to the UC2-IOL address list for more information on module communication (address 262) and module data (address 263).

* Refer to the respective address list for the setting values and setting details of each connection module

1. Check the number of the module to check or change the setting value.

Check the number of the module for which the setting value will be checked or changed. The modules are numbered (1, 2, 3, etc.) according to their distance from the UC2-IOL, starting with the farthest (leftmost side).

Example: With 5 fiber amplifiers and 1 displacement sensor amplifier unit connected

2. Check the module address and communication data length for the setting value to be checked or changed.

Refer to the address list of the module for which the setting value will be checked or changed, and check the module address and communication data length of the setting value.

Example:

| To check the D3RF display setting | Module address: 100 <br> Data length: 2 |
| :--- | :--- |
| To perform D3WF first-point teaching | Module address: 202 <br> Data length: 2 |
| To check the CD22 near threshold | Module address: 130 <br> Data length: 2 |

3. Set the module number, module address, and communication data length being checked or changed to the UC2-

IOL Configure the module number, module address, and communication data length in the UC2-IOL module communication settings (address: 262).

Example:

| To check the display setting of the D3RF <br> (Module number: 1) | Module number (address: 262, Sub-address: 1): 1 <br> Module address (address: 262, Sub-address: 2): <br> 100 |
| :--- | :--- |
|  | Data length (address: 262, Sub-address: 3): 2 |

## . Check the setting value

To check the setting value, read the UC2-IOL module data: data (address: 263 , Sub-address: 1 ).

## Example:

If the display setting for the D3RF (module number: 1) Is setor
0x00, 0x01,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00
If the near threshold of the CD22 (module number: 3 ) is -3.00 $0 \times F E, 0 \times D 4,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00$
5. Change the setting value.

To change the setting value, write the target change value to UC2-IOL module data: data (address: 263, Sub-address: 1)
Example:

[^0]$0 \times 00,0 \times 01,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00$
$0 \times 04,0 \times D 2,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00,0 \times 00$

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## F/ASTUS <br> UC2-IOL

INDEX LIST

optex fa co.,LtD.

## Communication specifications

| Min. cyclet | ${ }^{2.2 \mathrm{~ms}}$ Coms (230.46pos) |  |
| :---: | :---: | :---: |
| Baud rate |  |  |
| Support | Yes |  |
| $10 .-$ Linkrevision | ${ }^{1.1}$ |  |
| Inputting process data length |  |  |
| Outputing process data length | 32 |  |
| Venderio | dee: 1076 | hex $0 \times 043$ |
| Device 10 | dee: 8007 | hex $0 \times 15001$ |

## Process Data Format

16 modules (13 analog outputs) (Index120: 0)










## 14 modules (14 analog outputs) (Index 120: 1)



## 16 modules (16 analog outputs) (Index 120: 2)








## Service Data




## Events

| code |  | Name | type | Desscription |
| :---: | :---: | :---: | :---: | :---: |
| dec | nex |  |  |  |
| 16912 | Oxa210 | Device emperature over-un | Warning | Claar source of heat |
|  | 0xa220 | Device emperature under-un | Waring | Insulate device |
|  | 0x1800 | Short Ciciution ax | Notitication | Short tiruito outputs |
| 645 | 0x1801 | Teach / value outo fspecified range | Notrication | Teach / distance value out of speafied range |
| 646 | 0x1802 | Invald modue order | Eror | Module 1.1 .16 must tolow the speacifed order ( 0.9 .0 D3FF - D3WF - CDA) |
| 647 | 0x103 | Motue count changed | Eror | Modul count has changed sine last power-up of the gateway device. |
| 6148 | 0x1804 | Invald modue comected | Eror | An ivalid not compatible modul has been connected to the gateway. |
|  |  |  |  |  |

## Errors

| code |  | Additional code |  | Name | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |
| 128 | 0,80 | 17 | 0x11 | Index notaviable | Access occurs toa note exsing index |
| 128 | $0 ; 80$ | 18 | 0x12 | Subindex notavalable | Access ocuus toante exssing s subindex |
| 128 | 0880 | 32 | 0x20 | Sevice temporaili not avalable | Parameeris not a cesesible due tothe curent state ofthe device epplicition |
| 128 | 0880 | 35 | 0x2 | Accoss denied | Witita access on a read-only parameter |
| 128 | 0880 | 48 | $0 \times 30$ | Parameieralue out frange | Witten parametervalue is outide its pemitite value range |
| 128 | 0880 | 51 | $0 \times 33$ | Parameter engit overun | Wirter poaraneier engsti s sabove its predefined length |
| 128 | 0880 | 52 | $0 \times 34$ | Parameererengtu underun | Wirter parameter enggti s sbelow it predefined length |
| 128 | 0,80 | 64 | 0x40 | Invalid arameier set |  |
| ${ }^{128}$ | 0880 | ${ }^{65}$ | 0x4 | nosisentrarat | Patameter ino onsistencies were |

## System command

| Index No. |  | Sub-index No. | Access | Name | Value/Range | Display ${ }^{2}$ | Defautualue |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| dec | ${ }_{0 \times 2}{ }^{\text {hex }}$ |  | w | System command | $\begin{aligned} & \text { 65: SP1 Teach } \\ & \text { 66: SP2 Teach } \\ & \text { 130: Restore Factory Settings } \end{aligned}$ |  |  |

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Compact Laser Displacement Sensor

## CD22 Series

OPTEX FA CO. LTD

## Module Address

| $\begin{array}{\|l} \hline \text { Address } \\ \hline \text { Dec } \\ \hline \end{array}$ | $\frac{\mathrm{No}}{\text { hex }}$ | Name | ${ }_{\substack{\text { Access } \\ 1 \\ 1}}^{\text {d }}$ | $\left\lvert\, \begin{gathered} \text { Format } \\ (\text { Offfset }) \end{gathered}\right.$ | $\underset{\left(\begin{array}{l} \text { (Byyte) } \end{array}\right.}{\substack{\text { (Ben }}}$ | Valuekange | Address for <br> CDA *2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $0 \times 1$ | Product Type | RO | Uint | 2 | $0 \times 011$ |  |
| 2 | 0x2 | Firmware Version | Ro | Uint |  | 0x0011 |  |
| 3 | 0×3 | Protocol Version | RO | UINT | 2 | 0x0000 |  |
| ${ }_{-}^{4}$ | 0x4 | Product Revision | RO | UINT | 2 | 0x0000 |  |
| 5 | 0x5 | Vendor Name | RO | STRING | 21016 | "OPTEX FA" |  |
| 6 | 0x6 | Product Name | Ro | STRING | 21032 | Product name |  |
| 7 | 0x7 | Product ID | RO | STRIING | 21032 | Product ID |  |
| 8 | $0 \times 8$ | User Tag Name(Max. 32 byes) | RW | STRING | 21032 |  |  |
| , | 0x9 | Operation Staus | RO | uint | 2 | 0: Initiaize 1: lde 2: Fexeute 3: For use by user |  |
| ${ }^{98}$ | $0 \times 62$ |  | RW | Uint | 2 |  |  |
| 100 | $0 \times 64$ | Threshold Near | RW | Uint | 2 | -Write a roitrary value: Deleiel last error code |  |
| 101 | $0 \times 65$ | Threshold Far | RW | Uint |  | -32788~32767 | $\checkmark$ |
| 102 | $0 \times 66$ | Output hysteresis | RW | UINT | 2 | 0~32767 | $\checkmark$ |
| 103 | $0 \times 67$ | Calculation flags | RW | Uint | 2 | 10: No calculation | $\checkmark$ |
| 104 | $0 \times 68$ | Calculation coefficient Add (Seting value for each comnected sensor) | RW | UINT | 2 |  |  |
| 105 | $0 \times 69$ | Calauluation coefficient Multiply (Setting value for each connected sensor) | RW | UiNT | 2 | -10000~10000 | $\checkmark$ |
| 106 | 0x6A | Calculation coefficient Divide (Setting value for each connected sensor) | Rw | UINT | 2 | ${ }^{1 \sim 32767}$ | $\checkmark$ |
| 107 | $0 \times 6 \mathrm{~B}$ | Monitor Calculation Values | Rw | Uint | ${ }^{2}$ | 0 : Sensor 2 measured value <br> 1: Calculated value | $\checkmark$ |
| 108 | $0 \times 6 \mathrm{C}$ | Calculation Values Head | RW | UINT | 2 |  |  |
| 109 | $0 \times 6 \mathrm{D}$ | Calculation Values Head | $\stackrel{\text { RW }}{ }$ | UINT | 2 | 1: Addition |  |
| 110 | $0 \times 6$ E | Calculation Valus Uuit let Head | ${ }_{\text {RW }}$ | UINT | 2 | 3: ${ }^{\text {2 Sububraction }}$ Abue | $\checkmark$ |
| 111 | $0 \times 6$ F | Calculation Values Unit lett Head2 | RW | UiNT | 2 | 3: Absolute value difference |  |
| 112 | 0x70 | 10 polarity | RW | unt | 2 | 0:PNP (N.O.) 1:NPN (N.O.) 2PNP (N.C.) 3:NPN (N.C.) | $\checkmark$ |
| 113 | 0x71 | Output Selection CH 1 | Rw | Uint | 2 | 0 No output |  |
| 114 | $0 \times 72$ | Output Selection CH2 | RW | Uint | 2 | 2: Calaulated value out of range on near side (L) 3: Calculatd value out of range on tar side (HI) |  |
| 115 | 0x73 | Output Selection CH3 | Rw | uint | 2 | 4: Calculated value out of range on far sid 4: within threshold range (GO) <br> 5: Sensor 1 out of range on near side (LO) <br> 6: Sensor 1 out of range on far side (HI) 7: Sensor 2 within threshold range (GO) <br> 8: Sensor 2 out of range on near side (LO) <br> 9: Sensor 2 out of range on far side (HI) | $\checkmark$ |
| 116 | $0 \times 74$ | Exteral input selection | RW | Uint | 2 | 0: No function <br> : Teaching (Far side on rising edge, near side on falling edge) <br> 2: BGS/FGS teaching <br> 3: Zero reset <br> Laser emission OFF | $\checkmark$ |
| 117 | 0x75 | Analog output selection | RW | unst | 2 | 1: Calculated value <br> 2: Sensor 1 <br> 3: Sensor 2 | $\checkmark$ |
| 118 | 0x76 | Analog scaing | Rw | UוNT | ${ }^{2}$ | 0: No scaling <br> 1: Scaling | $\checkmark$ |
| $\frac{119}{120}$ | 0x77 | Analog Scaling (max.) $10 \mathrm{~V} / 20 \mathrm{~mA}$ | $\stackrel{\text { RW }}{\text { RW }}$ | UINT | 2 | 32768~32767 | $\checkmark$ |
| 120 121 | 0x78 |  | Rw | uint | 2 |  | $\checkmark$ |
| 129 | $0 \times 81$ | Amplifier product code | RO | UINT | 2 | $0 \times 2503$ | $\checkmark$ |
| $\begin{array}{\|l\|l\|} \hline 130 \\ 131 \\ \hline \end{array}$ | - | Swithing point Near (Leap point Close) | $\stackrel{\text { RW }}{\text { RW }}$ | UINT | $\frac{2}{2}$ | Cos2-15-455:7499 to 7499 (in units of 1 mm ) |  |
| $\stackrel{132}{132}$ | ${ }^{0 \times 84}$ | Smiching point frar (Leap point Away) | RW | UINT | 2 |  |  |
| 133 | 0x65 | Tolerance ObSB | RW | UINT | 2 | CD22-15-485: 0 to 7499 (in units of $1 \mu \mathrm{~m}$ ) CD22-35-485: 0 to 2249 (in units of $10 \mu \mathrm{~m}$ ) CD22-100-485: 0 to 7499 (in units of $1 \mu \mathrm{~m}$ ) |  |


*1. RO=Read Only, R/W=ReadWrite, WO=Write Only
*2. Displacement Sensor Amplifier Unit

## Errors



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Displacement Sensor Amplifier Unit

## CDA Series

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## Module Address

| Address No. |  | Name | Access* | $\begin{aligned} & \begin{array}{l} \text { Format } \\ \text { (Offset) } \end{array} \\ & \hline \end{aligned}$ | $\begin{aligned} & \begin{array}{l} \text { Length } \\ \text { (Byte) } \end{array} \\ & \hline \end{aligned}$ | Value/Range |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| dec | hex |  |  |  |  |  |
| 100 | $0 \times 64$ | Threshold Near | RW | UINT | 2 | 32768~32767 |
| 101 | $0 \times 65$ | Threshold Far | RW | UINT | 2 | 32768~32767 |
| 102 | $0 \times 66$ | Output hysteresis | RW | UINT | 2 | 0~32767 |
| 103 | $0 \times 67$ | Calculation flags | RW | UINT | 2 | 0: No calculation 1: With calculation |
| 104 | 0x68 | Calculation coefficient Add (Setting value for each connected sensor) | R/W | UINT | 2 | -10000~10000 |
| 105 | $0 \times 69$ | Calculation coefficient Multiply (Setting value for each connected sensor) | R/W | UINT | 2 | 10000~100 |
| 106 | $0 \times 6 \mathrm{~A}$ | Calculation coefficient Divide (Setting value for each connected sensor) | RW | UINT | 2 | 1~32767 |
| 107 | $0 \times 6 \mathrm{~B}$ | Monitor Calculation Values | RW | UINT | 2 | 0 : Sensor 2 measured value 1: Calculated value |
| 108 | $0 \times 6 \mathrm{C}$ | Calculation Values Head1 | RW | UINT | 2 | 0: None |
| 109 | $0 \times 6 \mathrm{D}$ | Calculation Values Head2 | RW | UINT | 2 | 1: Addition |
| 110 | $0 \times 6 \mathrm{E}$ | Calculation Values Unit left Head1 | RW | UINT | 2 | 2: Subtraction |
| 111 | 0x6F | Calculation Values Unit left Head2 | RW | UINT | 2 | 3: Absolute value difference |
| 112 | 0x70 | I/O polarity | RW | UINT | 2 | $\begin{aligned} & \text { 0:PNP (N.O.) } \\ & \text { 1:NPN (N.O.) } \\ & \text { 2:PNP (N.C.) } \\ & \text { 3:NPN (N.C.) } \end{aligned}$ |
| 113 | 0x71 | Output Selection CH1 | RW | UINT | 2 | 0: No output <br> 1: Calculated value within threshold range (GO) |
| 114 | 0x72 | Output Selection CH2 | RW | UINT | 2 | 2: Calculated value out of range on near side (LO) 3: Calculated value out of range on far side (HI) |
| 115 | 0x73 | Output Selection CH3 | R/W | UINT | 2 | 4: Sensor 1 within threshold range (GO) <br> 5: Sensor 1 out of range on near side (LO) <br> 6: Sensor 1 out of range on far side (HI) <br> 7: Sensor 2 within threshold range (GO) <br> 8: Sensor 2 out of range on near side (LO) <br> 9: Sensor 2 out of range on far side (HI) |
| 116 | 0x74 | External input selection | RW | UINT | 2 | 0: No function <br> 1: Teaching (Far side on rising edge, near side on falling edge) <br> 2: BGS/FGS teaching <br> 3: Zero reset <br> 4: Laser emission OFF |
| 117 | 0x75 | Analog output selection | RW | UINT | 2 | 0: None <br> 1: Calculated value <br> 2: Sensor 1 <br> 3: Sensor 2 |
| 118 | 0x76 | Analog scaling | RW | UINT | 2 | $\begin{aligned} & \text { 0: No scaling } \\ & \text { 1: Scaling } \\ & \hline \end{aligned}$ |
| 119 | 0x77 | Analog Scaling (max.) $10 \mathrm{~V} / 20 \mathrm{~mA}$ | R/W | UINT | 2 | 32768~32767 |
| 120 | 0x78 | Analog Scaling (min.) $0 \mathrm{~V} / 4 \mathrm{~mA}$ | RW | UINT | 2 | 32768~32767 |
| 121 | 0x79 | Baud rate <br> (Setting value for each connected sensor) | RW | UINT | 2 | 0: No connection <br> 1: 9.6 kbps <br> 2: 19.2 kbps <br> 3: 38.4 kbps <br> 4: 57.6 kbps <br> 5: 115.2 kbps <br> 6: 230.4 kbps <br> : 312.5 kbps <br> 8: 468.75 kbps <br> 9: 500 kbps <br> 10: 625 kbps <br> 11:833.3 kbps <br> 12: 937.5 kbps <br> 13: 1250 kbps |
| 129 | $0 \times 81$ | Amplifier product code | RO | UINT | 2 | 0x2503 |

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MODULE ADDRESS LIST
Digital Fiber Amplifier

## D3RF Series

OPTEX FA CO. LTD.

## Module Address

| Address No. |  | Name | Access* | Format (Offset) | Length (Byte) | Value/Range |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| dec | hex |  |  |  |  |  |
| 1 | 0x1 | Product Type | RO | UINT | 2 | 0x0012 |
| 2 | 0x2 | Firmware Version | RO | UINT | 2 | 0x0200 or more |
| 3 | 0x3 | Protocol Version | RO | UINT | 2 | 0x0001 |
| 4 | 0x4 | Product Revision | RO | UINT | 2 | Ox0001 |
| 5 | 0x5 | Vendor Name | RO | STRING | 2 to 16 | "OPTEXFA" |
| 6 | 0x6 | Product Name | RO | STRING | 2 to 32 | Product name |
| 7 | 0x7 | Product ID | RO | STRING | 2 to 16 | Product ID |
| 8 | 0x8 | User Tag Name (Max. 32 bytes) | R/W | STRING | 2 to 32 | "'" |
| 9 | 0x9 | Operation Status | RO | UINT | 2 | 0: Initialize <br> 1: Idle <br> 2: Execute <br> 3: For use by user |
| 98 | 0x62 | Error Code Refer to the separate "Errors" table | R/W | UINT | 2 | - Read: Last error code <br> -Write arbitrary value: Delete last error code |
| 100 | 0x64 | Display | R/W | UINT | 2 | 0: Numeric display <br> 1: Bar display <br> 2: Percentage display |
| 102 | 0x66 | Teach-in mode CH1 | R/W | UINT | 2 | 0: 2-point teaching <br> 1:1-point teaching <br> 2: Through teaching |
| 103 | 0x67 | Teach-in mode CH2 | R/W | UINT | 2 | 3: Zone teaching <br> 4: Auto-teaching <br> 5: Percent teaching <br> 6: Zero percent teaching |
| 104 | 0x68 | Response Speed | R/W | UINT | 2 | $\begin{aligned} & 0: 1-\mathrm{HS}(22 \mu \mathrm{~s}) \\ & 1: 2-\mathrm{FS}(85 \mu \mathrm{~s}) \\ & 2: 3-\mathrm{ST}(250 \mu \mathrm{~s}) \\ & 3: 4-\mathrm{LG}(1 \mathrm{~ms}) \\ & 4: 5-\mathrm{PL}(2 \mathrm{~ms}) \\ & 5: 6-\mathrm{UL}(4 \mathrm{~ms}) \\ & 6: 7-\mathrm{EL}(8 \mathrm{~ms}) \end{aligned}$ |
| 105 | 0x69 | Gain | R/W | UINT | 2 | 0: Low power <br> 1: Medium power <br> 2: High power |
| 106 | 0x6A | MF-Input | R/W | UINT | 2 | 0: External teaching input <br> 1: Test input <br> 2: Synchronous input <br> 3: Counter reset input <br> 4: External all teaching input <br> 5: No function |
| 107 | 0x6B | Key Lock | R/W | UINT | 2 | 0: Unlock <br> 1: Lock level 1 (Full lock) <br> 2: Lock level 2 (Half lock) |
| 108 | 0x6C | Operation mode CH1 | R/W | UINT | 2 | O: L-on (Light ON) |
| 109 | $0 \times 6 \mathrm{D}$ | Operation mode CH2 | R/W | UINT | 2 | 1: D-on (Dark ON) |
| 110 | $0 \times 6 \mathrm{E}$ | Threshold level CH1 Lower Limit | R/W | UINT | 2 | 999 to 9999 <br> The writable range varies depending on the operation mode. |
| 111 | 0x6F | Threshold level CH1 Upper Limit | R/W | UINT | 2 | -999 to 9999 Accessible only in Zone teaching mode. |
| 112 | 0x70 | Threshold level CH2 Lower Limit | R/W | UINT | 2 | -999 to 9999 <br> The writable range varies depending on the operation mode. |
| 113 | 0x71 | Threshold level CH2 Upper Limit | R/W | UINT | 2 | -999 to 9999 Accessible only in Zone teaching mode. |


| Address No. |  | Name | Access* | Format (Offset) | Length (Byte) | Value/Range |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 114 | 0x72 | Timer setting CH1 | RW | UINT | ) | 0: OFF delay timer |
| 115 | 0x73 | Timer setting CH2 | RW | UINT | 2 | 1: One-shot timer |
| 116 | 0x74 | CH1 Off delay time | R/W | UINT | 2 |  |
| 117 | 0x75 | CH1 On delay time | RW | UINT | 2 | 0~9999:0~9999ms |
| 118 | $0 \times 76$ | CH2 Off delay time | RW | UINT | 2 | -1~-9:0.1~0.9ms |
| 119 | 0x77 | CH2 On delay time | R/W | UINT | 2 |  |
| 123 | 0x7B | Hysteresis | RW | UINT | 2 | 1~40 |
| 125 | 0x7D | ASC (Automatic Sensitivity Control) | R/W | UINT | 2 | 0: None <br> 1: Normal correction <br> 2: High-speed correction <br> 3: Max. speed correction |
| 126 | 0x7E | Energy Saving | RW | UINT | 2 | 0: Standard <br> 1: Turn off display automatically <br> 2: Emission cycle $\times 2$ <br> 3: Display and emission cycle |
| 127 | 0x7F | Reverse display | R/W | UINT | 2 | 0: Standard 1: Inverted display |
| 200 | 0xC8 | Store zero-reset | wo | Byte | 2 | 0 to 65535: Execute |
| 201 | 0xC9 | Cancel zero-reset | WO | Byte | 2 | 0 to 65535: Execute |
| 202 | 0xCA | Teach-in 1-point | WO | UINT | 2 | 1: Output 1 teaching |
| 203 | 0xCB | Teach-in 2-point | WO | UINT | 2 | 2: Output 2 teaching |
| 210 | 0xD2 | Warm start Reset | WO | UINT | 2 | 3: Restart |
| 211 | 0xD3 | Return to top menu | wo | Byte | 2 | Execute with written value |
| 212 | 0xD4 | Factory Reset | wo | UINT | 2 | 3: Initialize (Allowed only when un |

* RO=Read Only, RW=ReadWrite, WO=Write Only


## Errors



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MODULE ADDRESS LIST
White LED Digital Fiber Amplifier

## D3WF Series

OPTEX FA CO. LTD.

## Module Address

| Address No. |  | Name | Access* | Format (Offset) | Length(Byte) | Value/Range |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| dec | hex |  |  |  |  |  |
| 1 | 0x1 | Product Type | RO | UINT | 2 | 0x0012 |
| 2 | 0x2 | Firmware Version | RO | UINT | 2 | 0x0100 |
| 3 | $0 \times 3$ | Protocol Version | RO | UINT | 2 | 0x0001 |
| 4 | 0x4 | Product Revision | RO | UINT | 2 | 0x0001 |
| 5 | 0x5 | Vendor Name | RO | STRING | 2 to 16 | "OPTEX FA" |
| 6 | $0 \times 6$ | Product Name | RO | STRING | 2 to 32 | Product name |
| 7 | 0x7 | Product ID | RO | STRING | 2 to 16 | Product ID |
| 8 | 0x8 | User Tag Name(Max. 32 bytes) | R/W | STRING | 2 to 32 | User ID (Max. 32 characters) |
| 9 | 0x9 | Operation Status | RO | UINT | 2 | 0 : Initialize <br> 1: Idle <br> 2: Execute <br> 3: For use by user |
| 98 | 0x62 | Error Code <br> Refer to the separate "Errors" table. | R/W | UINT | 2 | - Read: Last error code <br> - Write arbitrary value: Delete last error code |
| 100 | 0x64 | Display | R/W | UINT | 2 | 0 : Numeric display <br> 1: Bar display <br> 2: Percentage display |
| 102 | 0x66 | Teach-in mode CH1 | R/W | UINT | 2 | 0: 1-point teaching |
| 103 | 0x67 | Teach-in mode CH2 | R/W | UINT | 2 | 1:2-point teaching <br> 2: Dynamic teaching |
| 104 | 0x68 | Response speed | R/W | UINT | 2 | $\begin{aligned} & 0: 16 \mu \mathrm{~s} \\ & 1: 200 \mu \mathrm{~s} \end{aligned}$ |
| 105 | 0x69 | Gain | R/W | UINT | 2 | 0: Low power <br> 1: Standard power <br> 2: High power <br> 3: Automatic power |
| 106 | 0x6A | MF Input | R/W | UINT | 2 | 0 : Extended input <br> 1: All teaching (master only) <br> 2: Light ON/Dark ON switching <br> 3: Test input <br> 4: Off |
| 107 | 0x6B | Key Lock | R/W | UINT | 2 | 0 : Cancel <br> 1: Lock <br> 2: Lock for non-extended input |
| 108 | 0x6C | Operation mode CH1 | R/W | UINT | 2 | 0: Auto |
| 109 | 0x6D | Operation mode CH2 | R/W | UINT | 2 | $\begin{aligned} & \text { 1: L-on (Light ON) } \\ & \text { 2: D-on (Dark ON) } \end{aligned}$ |
| 110 | 0x6E | Threshold level CH1 Lower Limit | R/W | UINT | 2 | -999 to 9999 |
| 112 | 0x70 | Threshold level CH2 Lower Limit | R/W | UINT | 2 | The writable range varies depending on the operation mode. |
| 114 | 0x72 | Timer setting CH1 | R/W | UINT | 2 | 0: Delay OUT |
| 115 | 0x73 | Timer setting CH2 | R/W | UINT | 2 | 1: Individual |
| 116 | 0x74 | CH1 Off delay time | R/W | UINT | 2 |  |
| 117 | 0x75 | CH1 On delay time | R/W | UINT | 2 | 0~9999:0~9999ms |
| 118 | 0x76 | CH2 Off delay time | R/W | UINT | 2 | -1~-9:0.1~0.9ms |
| 119 | 0x77 | CH2 On delay time | R/W | UINT | 2 |  |
| 121 | 0x79 | Synchronization | R/W | UINT | 2 | 0: Asynchronous <br> 1: Synchronous |
| 123 | 0x7B | Sensitivity | R/W | UINT | 2 | $\begin{aligned} & 0: 10 \% \\ & 1: 20 \% \\ & 2: 50 \% \end{aligned}$ |


| Address No. |  | Name | Access* | Format (Offset) | $\begin{aligned} & \begin{array}{l} \text { Length } \\ \text { (Byte) } \end{array} \\ & \hline \end{aligned}$ | Value/Range |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 125 | 0x7D | ASC (Automatic Sensitivity Control) | R/W | UINT | 2 | $\begin{aligned} & \text { 0:OFF } \\ & \text { 1:ON } \end{aligned}$ |
| 126 | 0x7E | Eco mode | R/W | UINT | 2 | $0: \text { OFF }$ 1:ON |
| 127 | 0x7F | Reverse display | R/W | UINT | 2 | 0 : Normal display <br> 1: Inverted display |
| 200 | 0xC8 | Store zero-reset | wo | Byte | 2 | Execute with write operation |
| 201 | 0xC9 | Cancel zero-reset | WO | Byte | 2 | Execute with write operation |
| 202 | 0xCA | Teach-in 1-Point | WO | UINT | 2 | 1: Output 1 teaching |
| 203 | 0xCB | Teach-in 2-Point | WO | UINT | 2 | 2: Output 2 teaching |
| 210 | 0xD2 | Warm start Reset | WO | UINT | 2 | 3: Restart |
| 211 | 0xD3 | Return to top menu | WO | Byte | 2 | Execute with write operation |
| 212 | 0xD4 | Factory Reset | wo | UINT | 2 | 3: Initialize (Allowed only when |

* RO=Read Only, RW=ReadWrite, WO=Write Only


## Errors

| High-order byte |  | Low-order byte |  | Description |
| :---: | :---: | :---: | :---: | :---: |
| dec | hex | dec | hex |  |
| 0 | 0x0 | 0 | $0 \times 0$ | No error |
| Applicable address number |  | 1 | 0x1 | The address number is out of range. |
|  |  | 2 | 0x2 | The sub address number is not supported. |
| 0 | 0x0 | 3 | 0x3 | An attempt was made to write setting values to sensors that are all locked, or to initialize while locked. |
|  |  | 4 | $0 \times 4$ | The teaching target output specification value (1 or 2) is incorrect. |
|  |  | 5 | 0x5 | Teaching mode has no second teaching, or the first has not yet been executed. |
|  |  | 6 | 0x6 | The execution specification value (3) for restart and initialization is incorrect. |
| Applicable address number |  | 7 | 0x7 | An attempt was made to write a setting value that is out of range. |
|  |  | 8 | 0x8 | The setting value write operation failed. (Attempted to write a readonly setting value) |
| 0 | 0x0 | 11 | 0xB | The amount of light received during teaching was too low. |
|  |  | 12 | 0xC | The amount of light received during teaching was saturated. |
|  |  | 13 | 0xD | There was too little difference in the amount of light received during 2point teaching. |
|  |  | 15 | 0xF | A hardware error was detected. |

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Through-beam Edge Sensor

## TD1 Series

OPTEX FA CO. LTD

## Module Address

| Address No. |  | Name | $\begin{array}{\|c} \hline \text { Access } \\ \star 1 \end{array}$ | Format <br> (Offset) |  | Value/Range | Address for CDA*2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| dec | hex |  |  |  |  |  |  |
| 1 | $0 \times 1$ | Product Type |  |  |  |  |  |
| 2 | 0x2 | Firmware Version | RO | UINT | 2 | 0x1011 |  |
| 3 | 0x3 | Protocol Version | RO | UINT | 2 | 0x0 |  |
| 4 | 0x4 | Product Revision | RO | UINT | 2 | Product hardware version |  |
| 5 | 0x5 | Vendor Name | RO | STRING | 2 to 16 | "OPTEX FA" |  |
| 6 | $0 \times 6$ | Product Name | RO | STRING | 2 to 32 | Product name |  |
| 7 | 0x7 | Product ID | RO | STRING | 2 to 32 | Product ID |  |
| 8 | 0x8 | User Tag Name (Max. 32 bytes) | RW | STRING | 2 to 32 | User ID (Max. 32 characters) |  |
| 9 | 0x9 | Operation Status | RO | UINT | 2 | 0 : Initialize <br> 1: Idle <br> 2: Execute <br> 3: For use by user |  |
| 14 | 0xE | Serial Number | RO | STRING | 2 to 32 | Set using ASCII code |  |
| 98 | 0x62 | Error Status Refer to the separate "Errors" table. | RW | UINT | 2 | - Read: Last error code <br> - Write arbitrary value: Delete last error code |  |
| 100 | 0x64 | Threshold Near | R/W | UINT | 2 | 32768~32767 |  |
| 101 | 0x65 | Threshold Far | RW | UINT | 2 | -32768~32767 | $\checkmark$ |
| 102 | 0x66 | Output hysteresis | RW | UINT | 2 | 0~32767 | $\checkmark$ |
| 103 | 0x67 | Calculation flags | RW | UINT | 2 | 0: No calculation | $\checkmark$ |
| 104 | 0x68 | Calculation coefficient Add (Setting value for each connected sensor) | R/W | UINT | 2 |  |  |
| 105 | 0x69 | Calculation coefficient Multiply (Setting value for each connected sensor) | RW | UINT | 2 | 10000~10000 | $\checkmark$ |
| 106 | 0x6A | Calculation coefficient Divide (Setting value for each connected sensor) | RW | UINT | 2 | 1~32767 | $\checkmark$ |
| 107 | 0x6B | Monitor accumulations | RW | UINT | 2 | 0 : Sensor 2 measured value 1: Calculated value | $\checkmark$ |
| 108 | 0x6C | Calculation Values Head1 | RW | UINT | 2 | 0 : None |  |
| 109 | 0x6D | Calculation Values Head2 | RW | UINT | , | 1: Addition |  |
| 110 | 0x6E | Calculation Values Unit left Head1 | R/W | UINT | 2 | 2: Subtraction | $\checkmark$ |
| 111 | 0x6F | Calculation Values Unit left Head2 | RW | UINT | 2 | 3: Absolute value difference |  |
| 112 | 0x70 | I/O polarity | R/W | UINT | 2 | $\begin{aligned} & \text { 0:PNP (N.O.) } \\ & \text { 1:NPN (N.O.) } \\ & \text { 2:PNP (N.C.) } \\ & \text { 3:NPN (N.C.) } \end{aligned}$ | $\checkmark$ |
| 113 | 0x71 | Output Selection CH1 | RW | UINT | 2 | 0: No output <br> 1: Calculated value within threshold range (GO) |  |
| 114 | 0x72 | Output Selection CH2 | RW | UINT | 2 | 2: Calculated value out of range on near side (LO) <br> 3: Calculated value out of range on far side (HI) |  |
| 115 | 0x73 | Output Selection CH3 | RW | UINT | 2 | 4: Sensor 1 within threshold range (GO) <br> 5: Sensor 1 out of range on near side (LO) <br> 6: Sensor 1 out of range on far side (HI) <br> 7: Sensor 2 within threshold range (GO) <br> 8: Sensor 2 out of range on near side (LO) <br> 9: Sensor 2 out of range on far side (HI) | $\checkmark$ |
| 116 | 0x74 | External input selection | R/W | UINT | 2 | ```0 : No function 1: Teaching (Far side on rising edge, near side on falling edge) 2: BGS/FGS teaching 3: Zero reset 4: Laser emission OFF``` | $\checkmark$ |
| 117 | 0x75 | Analog output selection | R/W | UINT | 2 | 0: None <br> 1: Calculated value <br> 2: Sensor 1 <br> 3: Sensor 2 | $\checkmark$ |
| 118 | 0x76 | Analog scaling | RW | UINT | 2 | 0: No scaling 1: Scaling | $\checkmark$ |
| 119 | 0x77 | Analog Scaling (max.) $10 \mathrm{~V} / 20 \mathrm{~mA}$ | RW | UINT | 2 | 32768~32767 | $\checkmark$ |
| 120 | 0x78 | Analog Scaling (min.) $0 \mathrm{~V} / 4 \mathrm{~mA}$ | RW | UINT | 2 | 32768~32767 | $\checkmark$ |


| Address No. |  | Name | $\begin{gathered} \text { Access } \\ { }_{\star 1} \\ \hline \end{gathered}$ | $\begin{aligned} & \text { Format } \\ & \text { (Offset) } \end{aligned}$ | $\begin{array}{\|l} \begin{array}{l} \text { Length } \\ \text { (Byte) } \end{array} \\ \hline \end{array}$ | Value/Range | Address for CDA*2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| dec | hex |  |  |  |  |  |  |
| 121 | 0x79 | Baud rate <br> (Setting value for each connected sensor) | R/W | UINT | 2 | $0:$ No connection $1: 9.6 \mathrm{kbps}$ $2: 19.2 \mathrm{kbps}$ $3: 38.4 \mathrm{kbps}$ $4: 57.6 \mathrm{kbps}$ $5: 115.2 \mathrm{kbps}$ $6: 230.4 \mathrm{kbps}$ $7: 312.5 \mathrm{kbps}$ 88.468 .7 kkps $9: 500 \mathrm{kbps}$ $10: 625 \mathrm{kbps}$ $11: 83 . \mathrm{kkps}$ $12: 937.5 \mathrm{kbps}$ $13: 1250 \mathrm{kbps}$ | $\checkmark$ |
| 129 | $0 \times 81$ | Amplifier product code | RO | UINT | 2 | 0x2503 | $\checkmark$ |
| 134 | $0 \times 86$ | Average Number | RW | UINT | 2 | 1~128 |  |
| 135 | 0x87 | Measurement Type | R/W | UINT | 2 | 0: Edge positive 1: Edge negative 2: Width |  |
| 136 | 0x88 | Sampling rate | R/W | UINT | 2 | $0: 500 \mu$ (Fixed value) |  |
| 143 | 0x8F | Measuring direction | R/W | UINT | 2 | 0 : Top to Bottom 1:Buttom to Top |  |
| 144 | 0×90 | Zeroing value | RO | UINT | 2 | -9999~5000 |  |
| 152 | 0x98 | Sensitivity | R/W | UINT | 2 | 0 : Minimum value <br> 1: Second value <br> 2: Third value <br> 3: Fourth value <br> 4: Maximum value <br> 5: Adjustment value |  |
| 200 | 0xC8 | Save zero-reset | wo | Byte | 2 | Execute with write operation |  |
| 201 | 0xC9 | Cancel zero-reset | wo | Byte | 2 | Execute with write operation |  |
| 212 | 0xD4 | Factory Reset | wo | UINT | 2 | 3: Initialize |  |

*1. RO=Read Only, RW=Read/Write, WO=Write Only
*2. Displacement Sensor Amplifier Unit

## Errors

| High-order byte | Low-order byte |  | Description |
| :---: | :---: | :---: | :---: |
| dec ${ }^{\text {dex }}$ | dec | hex |  |
| 0x0 | 0 | $0 \times 0$ | No error |
| Applicable address number | 1 | $0 \times 1$ | The address number is out of range. |
|  | 2 | 0x2 | The sub address number is not supported. |
|  | 3 | 0x3 | The ETX code in the command string is invalid. |
|  | 4 | $0 \times 4$ | A checksum error was detected. |
|  | 5 | 0x5 | The command code is invalid. |
|  | 6 | 0x6 | A non-regulated parameter was specified. |
|  | 7 | 0x7 | An out of range numeric value was specified. |
|  | 8 | 0x8 | Reserved |
|  | 9 | 0x9 |  |

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## FAStus

INSTRUCTION MANUAL

## UC2-IOL



OPTEX FA CO.,LTD.


## NOTICE

$\qquad$





1. Included Accessories

- Mounting bracket


## 2. Dimensions

UC2-IOL (with mounting bracket equipped)

## 



## 3. I/O Circuit Diagrams



SIO mode (standard I/O mode) with push-pull


## 4. Part Names


5. Lists of Cables and Connectable Models

Connector cables
(For UC2-IOL and D3RF/D3WF series connector types)

| Series name | Model | Type |
| :---: | :---: | :---: |
| M84CN series | M84CN-2S | 2 mong |
| (M8,4.pin coonector | -5s | 5 mong |
|  | -10s | 10 mong |

## Fiber amplifier



Displacement sensor amplifier units


Displacement sensors/edge sensors

*These are lists of connectable models as of January 2020. There are plans to add prod
Ucts sequentiall, so contact OPTEX FA for details on models that are not listed here.

## 6. Installation

Installation on DIN rail or the included mounting bracket
Hook the indicator--side tab on the DIN rail or the included
nounting bracket (©), and then press dow mounting
locks (2).


Removal
While pressing the main unitin the direction of (D), ilit
the indicator side (2) to remove the main unit.

Inter-connecting with fiber amplifiers and displacement sensor amplifier units
To inter-connect all the units, sidide the fifier amplifiers and displacement sensor amplifier
units along the IIN rail that the UCL if a attached to.


## $\triangle$ CAUTION

- Be sure to turr off the power before performing this work.
- When inter-connecting, check. the ambient temperature and use the units within the operating range for the ambient temperature.
To prevent short-circ



## Installing end plates (sold separately)

To prevent the inter-connected units from coming loose, attach end plates (sold sepa-
rately; model: :EF--EBO-W 190 ) to the DiN rail so that they surround the inter-connected units and fix the end plates in place with screws.
Orient the end plates so that the producterside is against the unit and the fiber ampifi-
ers,
 se a tightening torque of $0.9 \mathrm{~N} \cdot \mathrm{~m}$ or less.

$\triangle$ CAUTION
When inter-connecting the unit to D3BF/D3WF series fiber amplifier and to CDA series displacement sensor amplifier units, be sure to connect the inter-connection master unit
on the efft end (ID $=1$ ). Ifan inter-connection slave unitit is conneected on the e lett end, the inter-connection connector will be exposed, causing inter ererence with the end plate. Allso,
fouling on or damage to the inter-connection connector may damage the fiber amplifiers.


## 7. Connecting

Connecting the connector cable (sold separately) Use M84CN-US M8 connector cable to connect to the 10 -Lin master unit.
Check the orientation of the connector pins on the unit side and on the connector cable
side and attach the cable correctly


The UC2 operates with a supply voltage of 18 to 24 VDC ( 12 to 24 VDC in SIO mode). Be sure toperhect the wiring to the 1 - Link master unit and to the power supply device
because incorrect wiring may cause a fire or damage the product.

Connecting UC2 to CDA units (connecting to CD22 and TD1 units)
To connect the UC2 to cD22 series laser displacement sensors and to TD 1 seriest trough-
beam edge sensors, connect through CDA series displacement sensor amplifier units. <Connection example>



## $\triangle$ CAUTION

ADA series power supply must be connected to a power sumply that is separate foom that tor the







## Connecting UC2 to D3RF/D3WF series

Usifthe inter-connection connectors to connect the UC2 to D3RF/D3WF series fiber am.

## Connecting power supply wires

When three or less fiber amplifiers are inter-connected to the UC2, the fiber amplifiers op-
 master unit on the left end to the same power supply as the 10 -Link master unit.


Fiber amplifier inter-connection order
When inter-connecting the unit to D3RF series and D3WF series fiber amplifiers, do so
with all the D3WF units closest to the unit and all the D3RF
units farthest away Connection example>
$\triangle$ CAUTION


- When inter-connecting the unit to fiber ampilifers be burre to cornectan inter. connection master unit

 : Can be acaured.





## Connecting UC2 to a combination of CDA series and

 D3RF/D3WF series units




## $\triangle$ CAUTION

- When in inter-cosmenectint


 - intomation tup to sensors can be acauried.


8. System Configuration Example


- The UC2 can be inter-connected to up to a total of 16 sensors. (One CDA displace

 - acquired.



## 9. Specifications







10. For details on the support tor the China RoHS directive the Administrative Mea
sure on the Control of Pa
he following websit htps://www.optex-fa.com/rons_cn/

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[^0]:    To perform D3WF (module number: 2) first-point teaching
    To set the near threshold of the CD22 (module number: 3 ) to 12.34

[^1]:    2. Supports the dispay yunction of op Prexfalo-Lnk masier
[^2]:    * RO=Read Only, RW=ReadWrite, WO=Write Only

